

The Real Time Clock

Built-in RTC with the HMS81C7332

INTRODUCTION

The HMS81C7332 has dual oscillator, main and sub-oscillator. The sub oscillator used to run 32.768 KHz crystal source, and we can make watch time interval interrupt then it is normally used as real time clock source, furthermore this device has power saving mode and one minute timer interrupt function, then we are able to lengthen the battery life with one minute interrupt and sub oscillator. The HMS81C7332 features three characteristics for RTC application as follows, power saving mode, wide operating voltage and one minute watch timer. Under sub oscillator active mode, its current is very low, 100uA roughly. And this device operates in wide voltage range, 1.8V ~ 5.5V. Therefore it can be able to be biased by normal battery. The watch timer function can make one minute interval interrupt. Under main power saving mode, the watch timer generates interrupt to wakeup main oscillator

and counts up the clock hour and minute. After calculating clock data, MCU switch on power saving mode again. Then we can minimise power consumption, because main oscillator works on several 10us long at every minute.

This RTC solution is an effective method which compose of one minute watch timer, power saving mode, sub colck and external interrupt. Compare to standalone RTC device, this HMS81C7332 built-in RTC solution is a cost effective RTC method.

DESCRIPTION

Figure 1 is a typical block diagram to apply the RTC application. The HMS81C7332 microcontroller is used and the oscillator are 4MHz as main clock and 32.768KHz as sub one. Figure 2. explains power consumption timing.

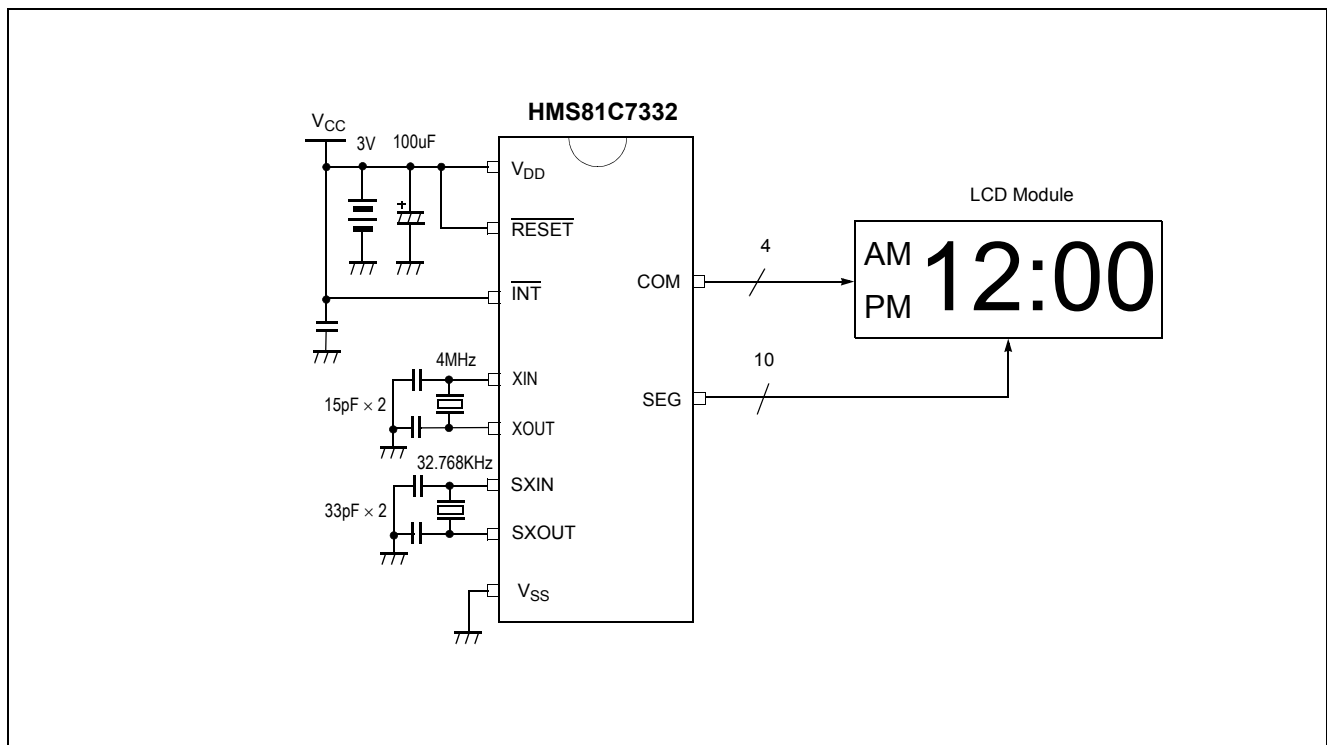


Figure 1. Circuit Block Diagram

HARDWARE

The operating voltage of HMS81C7332 is 1.8V to 5.5V, the lower level of V_{DD} , the better power saving effect. As an example, two AAA type battery voltage is enough to support V_{DD} . And RESET pin is connected to V_{DD} . The INT2 pin is used to detect main power off and on, which is triggered by falling edge or rising edge and is able to detect input level too. The watch timer generates one minute interval interrupt by sub oscillator source. And it has a function that wake up STOP mode. In this condition, the STOP mode means main oscillator stop, sub oscillator operates for watch timer. After STOP mode release, MCU run normal operating. The current consumption is 100uA at STOP mode and 1.5mA at normal operating. There are several power saving mode, STOP mode, sub active mode, sleep mode and other STOP mode which stops all oscillator. In this application, the power saving mode means STOP mode which run sub oscillator and watch

SOFTWARE

The RTC application program composes of three parts, Initialization, Power fail detection and power save mode switching, and watch timer interrupt subroutine.

The RTC initialization block is a part of firmware initial program by power-on reset, which starts watch timer working one minute interval interrupt, and enable external interrupt pin and interrupt pending at falling and rising edge.

The power fail detecting interrupt subroutine is composed of detecting main power fail or main power-on state, when MCU detects power fail, it switch on power saving mode, main oscillator stop, but sub oscillator is still alive because sub oscillator is the frequency source of RTC and LCD display. In this example, we use INT2 as power fail detection pin and this port is also used for level detection..

The watch timer interrupt subroutine updates real time clock data, hour and minute. When watch timer interrupt is pended, the MCU is waked up automatically and main oscillator restart working. As soon as finishing clock data

timer. When main power is off, MCU runs STOP mode, and every watch timer interrupt wakeup STOP mode for real time clock updating for short terms only. Sometimes low cost RTC application uses capacitor backup insted of battery backup. This style RTC requires large capacitor, but the backup time is limited. So we have to trade off cost and backup time.

In figure 2, T_{RTC} is the execution time of watch timer interrupt subroutine and T_{ISR} is the execution time of INT2 subroutine. Both T_{ISR} and T_{RTC} are very short term, 20 microseconds roughly.

update, MCU has to switch on power saving mode again, then main oscillator stop and power consumption is low. The main oscillator runs on short term T_{RTC} in Figure 2. therefore the average power consumption on the term of main power off is very low. The watch timer function is used to wake up power saving mode, and update clock hour and minute, and go back to power saving mode again.

An example program is attached to Appendix A.

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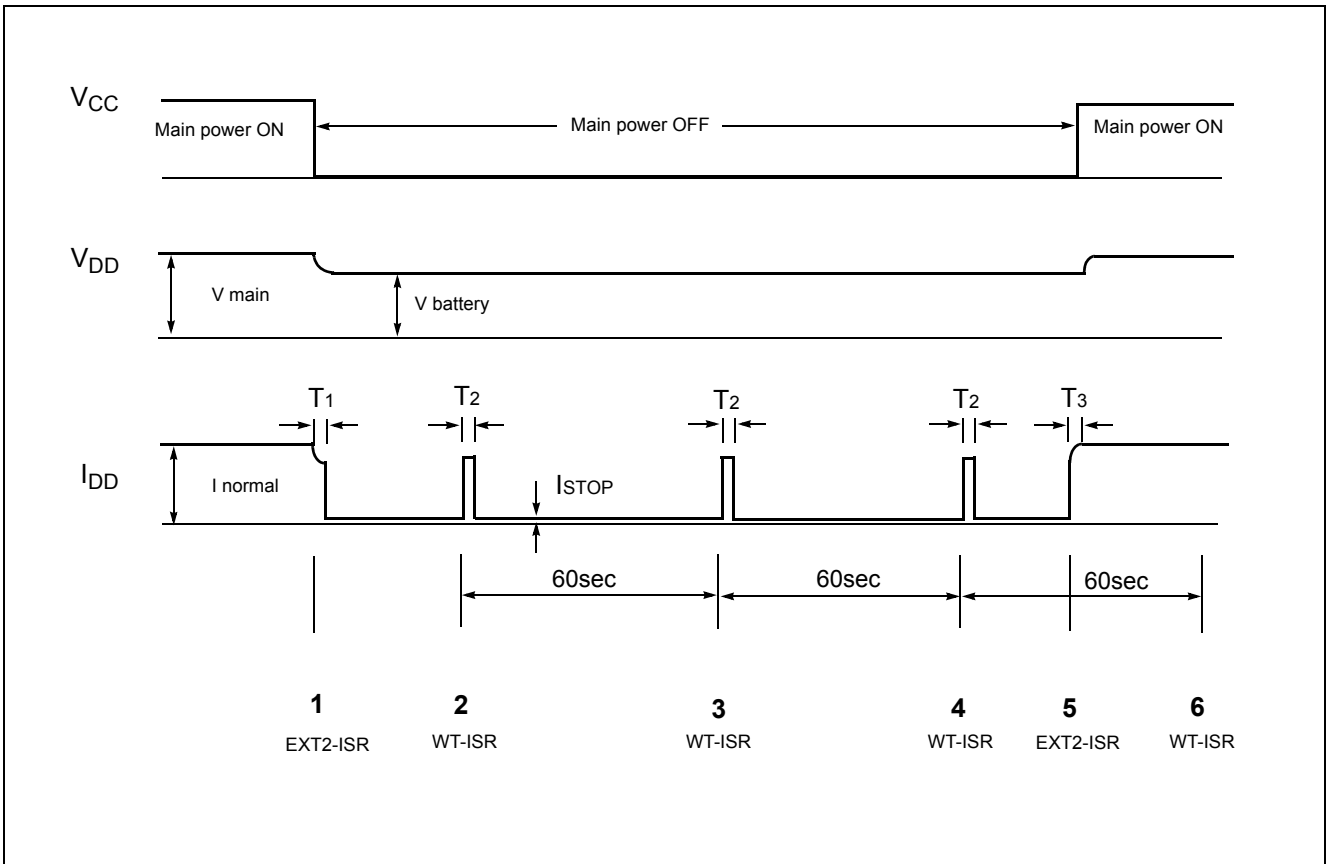


Figure 2. The RTC wake up Timing Diagram

Appendix A:

HMS800 series MICOM ASSEMBLER

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;*****
;Company      : MagnaChip Semiconductor Ltd. MCU Application Team
;Programmer   : BeeJay Lim
;-----
;TITLE        : The Real Time Clock Application
;Device       : HMS81C7332
;OSC          : Main 4MHz / Sub 32.768KHz
;*****

;-----
; Peripheral Register assignment

include      <HMS81C7332.H>      ;

p_PowerOn   equ      R11          ; high is power on state? (INT2 pin )

;-----
; User Memory(RAM) assignment

mStatus     ds      1             ;
f_PowerFail equ      0, mStatus   ; request power saving mode

mClk_Hour   ds      1             ; Clock Hour data
mClk_Minute ds      1             ; Clock Minute data

;-----
; external function proto type assignment

extrn label Process_Task1        ;
extrn label Process_Task2        ;
extrn label Process_Task3        ;
extrn label Clock_Display        ;

;-----
; Vector Table

ORG         0FFE0H
DW          Watch_Timer           ; Watch timer interrupt for clock update

ORG         0FFF6H
DW          Ext2_INT              ; External interrupt 2 for power fail

ORG         0FFFEH
DW          Program_Start         ; Power On Reset

;-----
; Main program

org         8000h

Program_Start:
DI          ; Disable global interrupt
ldx        #0FFh                       ;
txsp       ; stack point initialize
clrg       ; RAM0 page
.
.
.

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        ldm        R1, #00h          ;
        ldm        R1IO, #---- -0-b ; R11 input for level detection
        ldm        R1PU, #00h       ;
        ldm        R1OD, #00h       ;
        ldm        R1FUNC, #---- -1-b ; R11 define INT2
        .
        .
        .
        clr1       f_PowerFail      ; clear request power saving mode
        .
        ldm        WTMR, #1100_1100b ; Sub Clock fsub x 2e*14 x (count+1) =
        ldm        WTR, #1111_0111b ; 0x80 | (119+1)
        .
Wakeup_start:
        ldm        IENH, #---1 ----b ; INT2 enable
        ldm        IENL, #---1 ----b ; Watch Timer enable
        ldm        IRQH, #0          ; Clear All Interrupt Request
        ldm        IRQM, #0          ;
        ldm        IRQL, #0          ;
        ldm        IEDS, #--11 ----b ; Int2 both falling and rising Edge triggered
        .
        .
        ldx        #0FFh            ;
        txsp                          ; stack point initialize
        EI                          ; Enable global interrupt
;-----
main:
        clrg                          ; set Zero page
        .
        .
        call       !Process_Task1     ; execute task1
        call       !Process_Task2     ; execute task2
        call       !Process_Task3     ; execute task3
        .
        .
        .
PowerSaveMode:
        bbc        f_PowerFail, main ;
        clr1       f_PowerFail      ; clear request power saving mode in

        ldm        IENH, #---1 ----b ; INT2 enable
        ldm        IENL, #---1 ----b ; Watch Timer enable
        ldm        SSCR, #0Fh        ; sleep mode enable (sub clock only enable)
        nop                          ;
        stop       ; stop !!!

        nop                          ;
        nop                          ;
        jmp        !Wakeup_start      ;
;-----
Ext2_Int:
        bbc        p_PowerOn, Detect_fail ; Power fail detect and Power saving mode in !!!
Detect_On:
        .
        .
        jmp        !Wakeup_start      ; restart watch timer and interrupt

Detect_fail:
        .
        .

```

```

        .                ; now detect power fail state
        .                ; stop all power consumption path
        .                ;
set1    f_PowerFail     ; request power saving mode
        .                ;
reti   ;
;-----

Watch_Timer:
    push    A            ;

    inc     mClk_Minute  ;
    lda     mClk_Minute  ;
    cmp     #60          ; one hour?
    bcc    Clock_Updated ;
    ldm     mClk_Minute, #0 ;
    inc     mClk_Hour    ;
    lda     mClk_Hour    ;
    cmp     #24          ; one day ?
    bcc    Clock_Updated ;
    ldm     mClk_Hour, #0 ;

Clock_Updated:
    call    !Clock_Display ; clock display

    bbs     p_PowerOn, WatchTimer_end ; R11 == high or low ?

    set1    f_PowerFail     ; request power saving mode at power fail
WatchTimer_end:
    pop     A            ;
    reti   ;
;-----
;
;           end of file

```